

Summary of SIP-adus project (FY2015)

Name of the project	Development of V2V,V2I Communication Technology Toward the Automated Driving Systems
Responsible Organization	DENSO CORPORATION, Panasonic Corporation, PIONEER CORPORATION, The University of Electro-Communications

Hideaki NANBA, DENSO CORPORATION

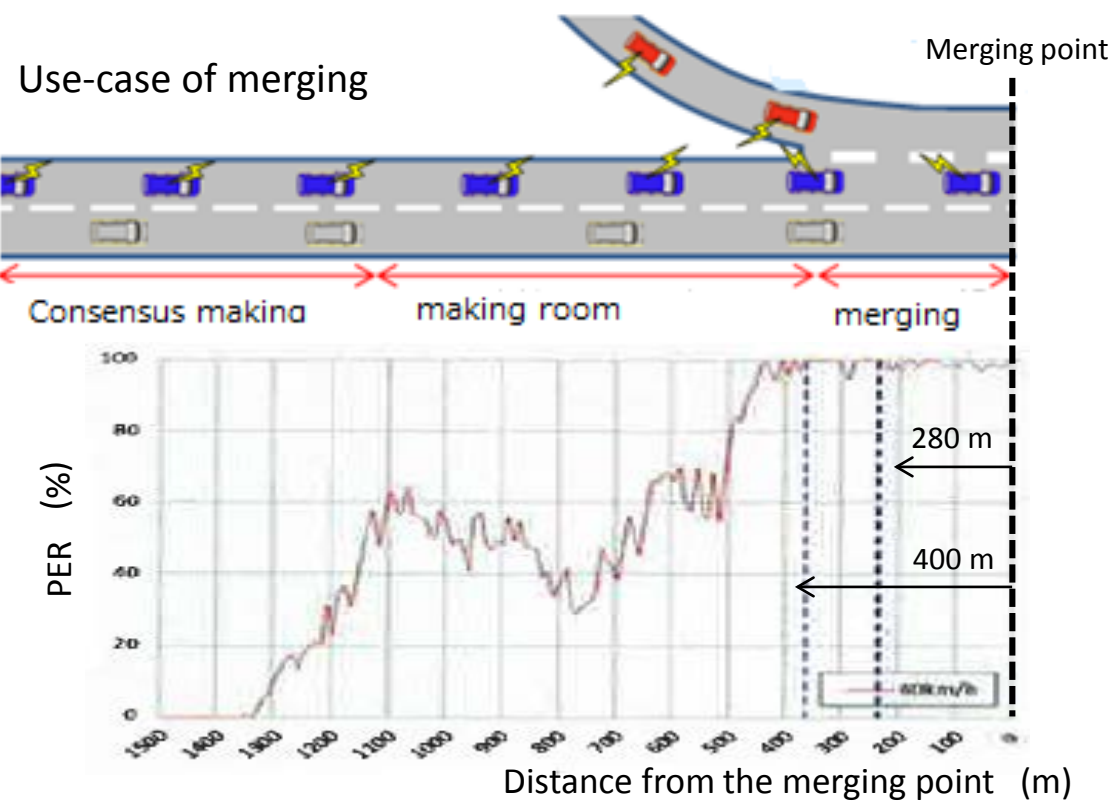
Object of the Project

Automated driving and connected cars will be achieved by applying ICT. To achieve this, V2V and V2I technology will be more sophisticated. Practical developing themes of highly reliable communication (low latency, PER etc.) and utilization of “look-ahead” information.

Project Summary

1. Communication performance and utilization of “look-ahead” information were evaluated in a merging scheme on the free-way.

Use-case of merging

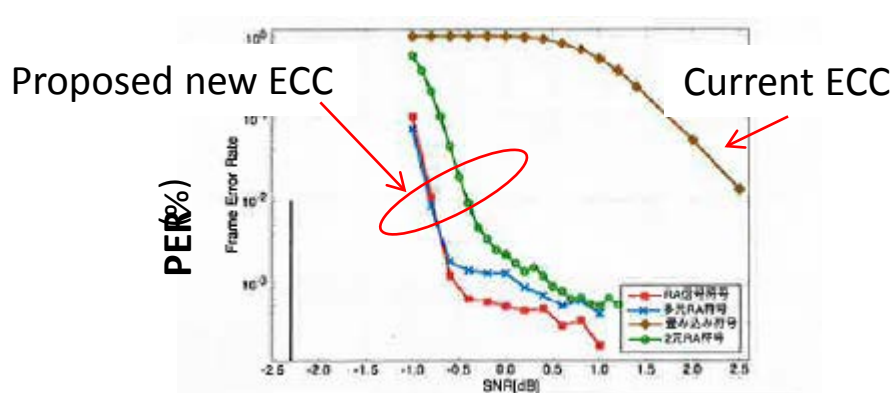


PER (%)

Distance from the merging point (m)

2. New communication technology (Cooperative distributed STBC scheme, Error Correcting codes) researched for use.

Proposed new ECC



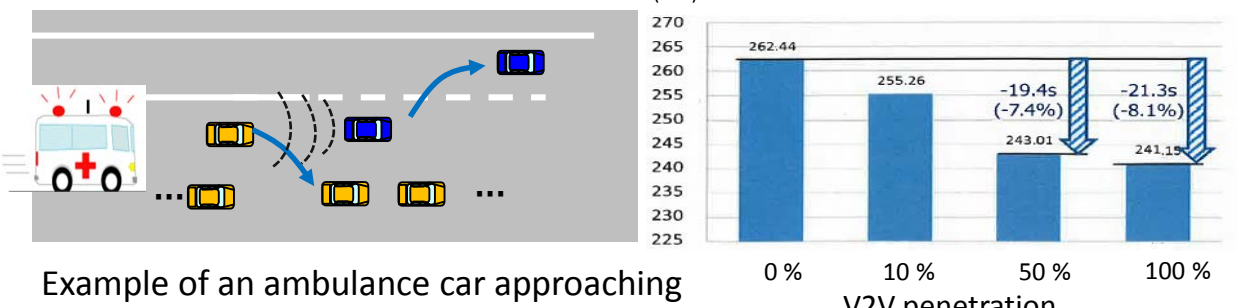
PER (%)

SNR [dB]

New Error Correcting Code (ECC)

3. The shortening the traveling time of an ambulance using V2V is researched with simulation.

Simulation result of the ambulance car traveling time

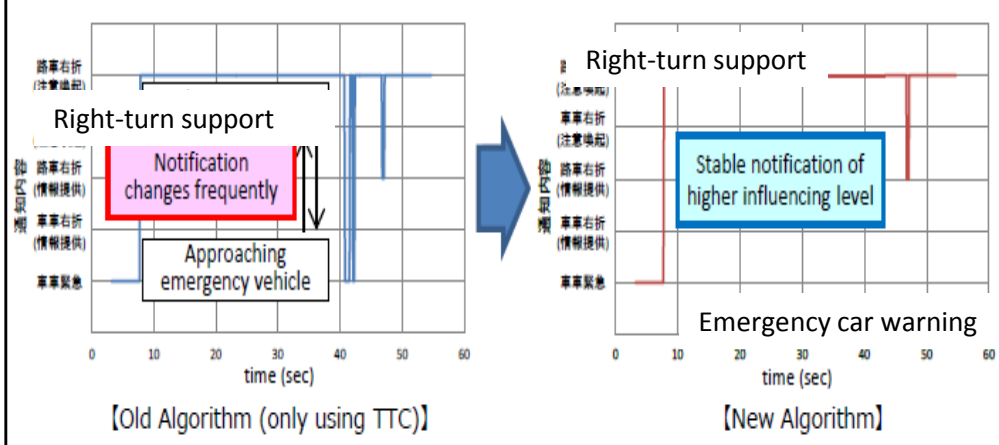


Example of an ambulance car approaching

V2V penetration	Traveling time (SEC)	Reduction
0 %	262.44	
10 %	255.26	
50 %	243.01	-19.4s (-7.4%)
100 %	241.19	-21.3s (-8.1%)

V2V penetration

4. The priority handling method proved its efficiency using the numerical value in the conflict overlapped information (Right-turn support and Emergency car warning).



Right-turn support

Emergency car warning

time (sec)

[Old Algorithm (only using TTC)]

[New Algorithm]

Warning notifications are improved using the priority handling method

Future plan

1. New communication technologies shall be proposed toward automated and connected driving systems.
2. “Look-ahead” information, its production and usage shall be proposed toward automated and connected driving systems.