

Second Phase of the Cross-Ministerial Strategic  
Innovation Promotion Program  
Automated Driving for Universal Services  
(SIP-adus)

the outline of  
the Tokyo Waterfront Area  
Field Operational Test report

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# 1. Background of the FOTs\*

\*FOTs Field Operational Tests

## (1) Objectives

○ To verify common technologies in inter-sectoral collaboration for the development of automated vehicles with dynamic environmental information provided through infrastructures such as traffic signal data on general roads and merging support information on expressways, along with to evaluate impact of these technologies on mixed traffic conditions.

○ To promote international cooperation and standardization and others, by organizing and reviewing worldwide and open forums.

## (2) Implemented

○ from October 2019 to the end of March 2021

## (3) Infrastructures and on-board units installed



### Waterfront city area with

- Traffic signal data from deployed ITS roadside units
- High Precision 3D map linked with the traffic signal data
- others



### Haneda airport area with

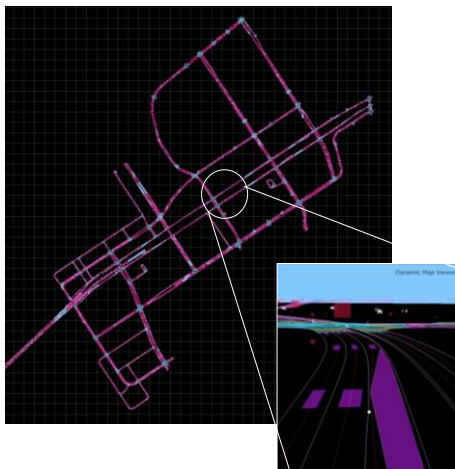
- Traffic signal data from deployed ITS roadside units
- Lanes magnetic markers disposed, provisional bus stops \*
- Reserved lanes\*



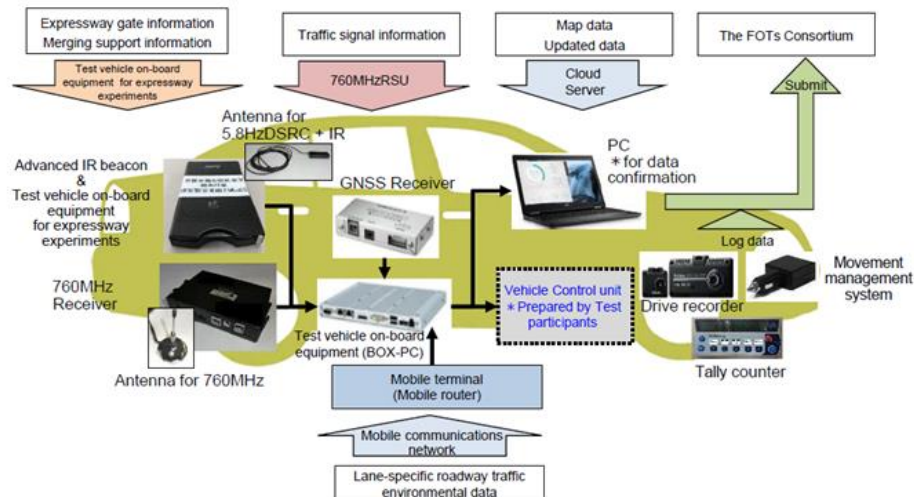
### Expressways connecting HND and Waterfront city area with

- Merging support information
- ETC gate status information
- Lane-level traffic regulation information and others

Each color on the map corresponds to the test area descriptions



High Precision 3D map image  
in Waterfront city area



Network structure for On-board unit in FOTs

## (4) Participants

○29 institutions including domestic and foreign automobile manufacturers, auto parts suppliers, universities, start-ups and others



Alphabetical order. A total of 29 institutions





## 2. Waterfront City area (traffic signal information)

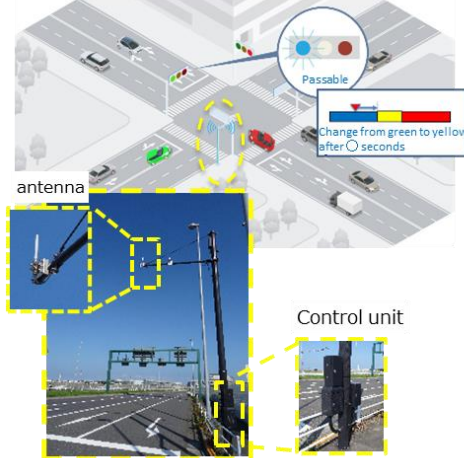
### Goal

**A society with traffic safety secured by minimum accidents**

### How

Distribution of data for:

- Real time signal color
- Time in seconds remaining to a next color

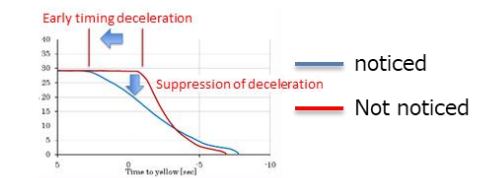


### Result

- Systems successfully recognized the signal colors even under bad weather, backlight and other indistinct circumstances



- Vehicles safely and smoothly stopped without hard braking, by noticed timing of signal color change



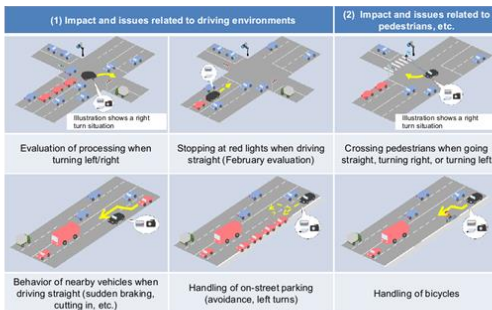
## 3. Waterfront city area (Impact assessment )40,

### Goal

**Smooth merging to general roads under mixed traffic for automated vehicles**

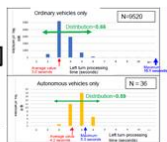
### How

- Clarification of impact caused by merging automated vehicles under actual traffic mixed with conventional vehicles and pedestrians

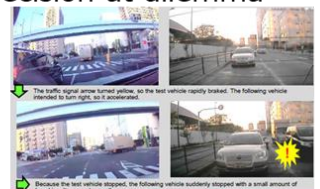


### Result

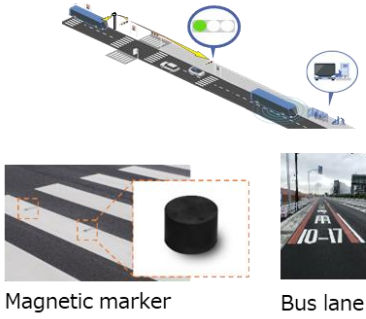

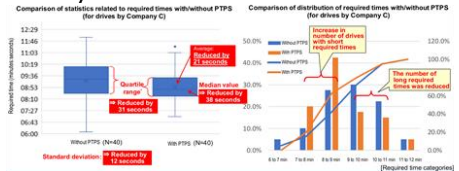
- No significant change found on traffic volume and pedestrian behaviors for automated cars' left and right turn at intersections



- Hard braking caused by vehicles following automated cars, of which the drivers made another decision at dilemma zone

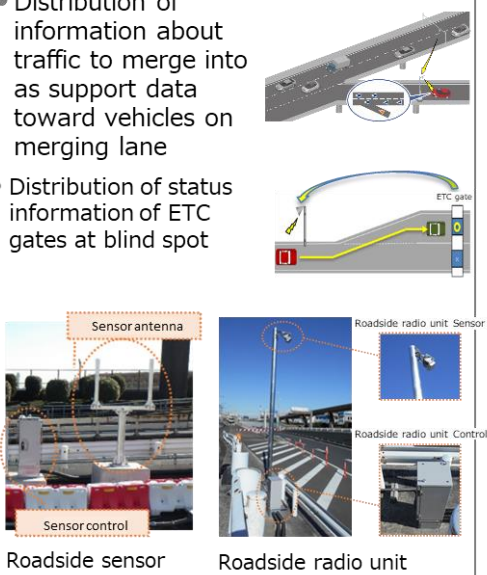




## 4. Haneda Airport area (next generation public transportation system)

Goal	<ul style="list-style-type: none"> <li>● Friendly bus for elderly and people with disabilities, realizing right positioning at stops and slower accel-brake control</li> <li>● Punctual and express transport service with bus priority signal</li> </ul>
How	<ul style="list-style-type: none"> <li>● Deployment of magnetic markers for position estimation and auto start-stop-turn control</li> <li>● Application of bus priority policy with PTPS for signal information distribution and "Go" signal time extension by network communication and with reserved lanes</li> </ul> <div data-bbox="239 546 601 865">  <p>Magnetic marker</p> <p>Bus lane</p> </div>
Result	<ul style="list-style-type: none"> <li>● Positioning of bus realized at stops right and close enough for wheelchair access without support</li> </ul> <div data-bbox="1048 440 1379 581">  </div> <ul style="list-style-type: none"> <li>● Shorter average travel time and more punctuality realized with the systems</li> </ul> <div data-bbox="925 701 1379 871">  </div>

\* FOTs for "Next generation transport system" with Level 4 closed in Nov. 2020

## 5. Metropolitan Expressway (merging support / ETC gate information)

Goal	<b>Smoother driving at merging points on Expressways</b>
How	<ul style="list-style-type: none"> <li>● Distribution of information about traffic to merge into as support data toward vehicles on merging lane</li> <li>● Distribution of status information of ETC gates at blind spot</li> </ul> <div data-bbox="219 1271 701 1848">  <p>Sensor antenna</p> <p>Sensor control</p> <p>Roadside sensor</p> <p>Roadside radio unit</p> <p>Roadside radio unit Sensor</p> <p>Roadside radio unit Control</p> </div>
Result	<ul style="list-style-type: none"> <li>● Traffic correctly recognized enough in advance even at merging points with walls blocking the view</li> </ul> <div data-bbox="1133 1398 1358 1524">  </div> <ul style="list-style-type: none"> <li>● ETC gate status data caught and resulted to define a lane to get into before recognizing the oncoming gate</li> </ul> <div data-bbox="1133 1663 1379 1848">  </div>